

# **Rotor RAU**





e-mail: spid@spid.net.pl <u>www.spid.net.pl</u>

# **DESCRIPTION**

Rotor works with controller Rot1Prog. It it can be used for lightweight construction, such as Yagi and heavy shortwave antennas. It is based on the worm gear, worm and worm wheel made of steel (as pictured). These features ensure long life and durability of the device. Its advantage is the possibility to adjust the worm and worm wheel clamping, clearing backlash in the drive mechanism, which may be necessary in the case of wear and tear after long-term use. The device surface is covered with powder coating, effectively protecting against corrosion. Range trading is protected by limit switches.

# **SPECIFICATIONS**

| Rotation angle:         | 360 +/- 180 º    |  |  |
|-------------------------|------------------|--|--|
| Rotation time for 360°: | 45 sek.          |  |  |
| Electric motor:         | 12 V DC          |  |  |
| Weight Antenna rotor:   | 8 Kg             |  |  |
| Encoder Type:           | Magnetic 4 pulse |  |  |
|                         | /HR 32 pulse     |  |  |
| Vertical load:          | 160 Kg           |  |  |
| Rotating torque:        | 900              |  |  |
|                         | *1800            |  |  |

# CONTROLLERS WORKING WITH MACHINE

ROT 1



The controller works with all motorized type RAU and RAK and also with all motorized having a pulse output. The controller was also created for those who constructed rotor by themselves or are working on equipment brought from abroad (controller software can be adapted to any structure in which the actuator is a pulser or REED.

To control using a computer there is specially prepared program ham radio SPID.LOG

#### **Controller Features:**

- Manual operation;
- Semi-automatic operation (you write angle without rotating the rotor, and after 2 seconds the rotor starts to given angle;
- Automatic operation (full control from your PC throughout SpidLog software program).

### **Additional features for Canada version:**

 MEMORY function (you can write 6 angles to memory that can be directly selected by buttons on the mouse). This feature allows you to quickly select a direction for example in competition.

ATTENTION. The mouse is not a computer mouse. It only looks similiar.Do not connect it to your computer!!!!

### **TECHNICAL SPECIFICATIONS:**

| Power supply: | 12V - 18V DC/0,5A - 1,5A external power supply required |  |  |
|---------------|---|--|--|
| Input Signal: | pulse version - pulses                                  |  |  |
| Supply:       | Electronic -180 +180 degrees                            |  |  |
| Dimensions:   | 120 x 35 x 220 mm                                       |  |  |
| Output:       | COM 9-pin connector to connect the PC                   |  |  |
|               | (RS232, 1200 baud, 1 stop bit, no parity).              |  |  |

### MD-01



MD-01 is an electronic control unit for rotating the rotors. It is a multifunctional device that allows for different combinations of settings work. The controller can be connected to individual rotors (eg, two rotors azimuth) or double (one rotor azimuth / elevation). The basic layout provides work with DC motors.

### Controller parameters:

- Controller MD-01 supply voltage 15 VDC (Imax 2A),
- Rotor supply voltage 12-14 VDC (Imax 40 A),
- Maximum supply voltage of a single motor up to 20 A.
- 2 RS232 ports
- 1 USB host port
- 1 USB device visible in the system as a virtual COM port.
- 1 RJ45 Ethernet port.

### **MD-02**



MD-02 is an electronic control unit for rotating the rotors. It is a multifunctional device that allows for different combinations of settings work. The controller can be connected to individual rotors (eg, two rotors azimuth) or double (one rotor azimuth / elevation). The basic layout provides work with DC motors.

### Controller parameters:

- Controller MD-01 supply voltage 15 VDC (Imax 2A),
- Rotor supply voltage 12-14 VDC (Imax 40 A),
- Maximum supply voltage of a single motor up to 20 A.
- 2 RS232 ports
- 1 USB host port
- 1 USB device visible in the system as a virtual COM port.
- 1 RJ45 Ethernet port.

# COMPARISON OF AVAILABLE MACHINES

| Rotator<br>Comparison<br>Table | RAU and<br>RAU/HR<br>( 18 V )<br>*(24V) | RAK and<br>RAK/HR<br>(18V)<br>*(24V) | BIG RAK<br>and<br>BIG-<br>Rak/HR | RAS and<br>RAS/HR<br>(18V)<br>*(24V) | BIG-RAS and<br>BIG-<br>RAS/HR<br>(18V) |
|--------------------------------|---|--------------------------------------|----------------------------------|--------------------------------------|--|
|                                |   |                                      | (18V)<br>*(24V)                  |                                      | *(24V)                                 |
| Rotating torque                | 900<br>*1800                            | 1.800<br>*3.240                      | 8.000<br>*8.000 **               | 1.800<br>*3.240                      | 8.000<br>*8.000 **                     |
| Braking torque                 | 8.000                                   | 14.000                               | 24.000                           | 14.000                               | 24.000                                 |
| Vertical load                  | 350 lbs                                 | 550 lbs                              | >700 lbs                         | 550 lbs                              | >700 lbs                               |
| Break type                     | Double worm                             | Double worm                          | Double<br>worm                   | Double worm                          | Double worm                            |
| Carter                         | Metal                                   | Metal                                | Metal                            | Metal                                | Metal                                  |
| Gear                           | Metal                                   | Metal                                | Metal                            | Metal                                | Metal                                  |
| Mast plate                     | Metal                                   | Metal                                | Metal                            | Metal                                | Metal                                  |
| Reduction ratio                | 3300 / 1                                | 4950 / 1                             | 6120 / 1                         | 4950/1                               | 6120 / 1                               |
| Encoder type                   | Magnetic 4                              | Magnetic 6                           | Magnetic 6                       | Magnetic 6                           | Magnetic 6                             |
|                                | pulse                                   | pulse                                | pulse                            | pulse                                | pulse                                  |
|                                | /HR 32 pulse                            | /HR 32 pulse                         | /HR 32 pulse                     | /HR 32 pulse                         | /HR 32 pulse                           |
| Precision                      | 1º / 1.0º                               | 1º / 1.0º                            | 0.59 / 0.59                      | 1º / 1.0                             | 0.5º / 0.5º                            |
|                                | /HR 0,1º /<br>0.1º                      | /HR 0,1º /<br>0.1º                   | /HR 0,1º /<br>0.1º               | /HR 0,1º /<br>0.1º                   | /HR 0,1º /<br>0.1º                     |
| Rotation angle                 | 360º +/- 180º                           | 360º +/- 180º                        | 360º +/-<br>180º                 | 360º +/- 180º                        | 360º +/- 180º                          |
| Rotation time                  | 45 sek                                  | 90 sek *45                           | 240 sek *                        | 90 sek *45                           | 240 sek *145                           |
| for 360°                       |   | sek                                  | 145sek                           | sek                                  | sek                                    |
| Electric motor                 | 12 Vdc                                  | 12 Vdc                               | 12 Vdc                           | 12 Vdc                               | 12 Vdc<br>/HR 24 Vdc                   |
| Environment                    | -20° +50°                               | -20° +50°                            | -20° +50°                        | -20° +50°                            | -20° +50°                              |
| Weight                         | 8 kg                                    | 12 kg                                | 15kg                             | 19kg                                 | 25kg                                   |
| Antenna rotor                  |   |                                      |                                  |                                      |  |
| Weight Digital                 | Rot1Prog- 1,5                           | Rot1Prog- 1,5                        | Rot1Prog-                        | Rot2Prog- 2                          | Rot2Prog- 2                            |
| Rotator                        | kg                                      | kg                                   | 1,5 kg                           | kg                                   | kg                                     |
| Controller                     | MD-02 – 4 kg                            | MD-02 – 4 kg                         | MD-02 – 4                        | MD-02 – 4 kg                         | MD-02 – 4 kg                           |
|                                | MD-01 – 5 kg                            | MD-01 – 5 kg                         | kg<br>MD-01 – 5<br>kg            | MD-01 – 5 kg                         | MD-01 – 5 kg                           |